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## What is BFLOAT16

## FP16 based training (GPUs):

Int16 based training (KNM/1 ${ }^{\text {st }}$ Nervana):



Figure 4. Distributions of tensor scales in a deep neural network and their evolution during training.


## The History Of BFLOAT16



## Bfloat16 on Intel Architecture

BF16 instructions for Cooper Lake now public at: https://software.intel.com/en-us/intel-architecture-instruction-set-extensions-programming-reference

3 Instructions:

- VNNI-Style dot-product with FP32 accumulate
- 2 FP32->BF16 converts (RNE) for 1024bits and



## What about combining data formats?

- Concept behind double-double: pair two doubles together and do "careful calculations" to keep track of over 100+ bits of accuracy.
- Why not do the same thing with bfloat16?
- We can have a single BF16, denoted bx1 and have roughly 8-bits of accuracy
- We can have a pair of BF16s, denoted bx2, and roughly 16-bits of accuracy
- We can have a triplet of BF16s, denoted bx3, and roughly 24-bits of accuracy
- This is comparable to FP32!
- This is not identical to FP32!
- Especially interesting for inner-products as we have a FP32 accumulator


## Creating Doubles or Triplets Very Easy (Compared to Double-Double Algorithms)

$$
\begin{aligned}
& b^{(0)}=\left(\mathcal{B}_{16}\right) a \\
& b^{(1)}=\left(\mathcal{B}_{16}\right)\left(\left(\mathcal{F}_{32}\right)\left(a-\left(\mathcal{F}_{32}\right) b^{(0)}\right)\right) \\
& b^{(2)}=\left(\mathcal{B}_{16}\right)\left(\left(\mathcal{F}_{32}\right)\left(a-\left(\mathcal{F}_{32}\right) b^{(0)}-\left(\mathcal{F}_{32}\right) b^{(1)}\right)\right)
\end{aligned}
$$

We can write every single precision number using this split:

- $b^{(0)}$ is bfloat16 and contains the most significant bits
- $b^{(1)}$ is bfloat16 and contains the next significant bits
- $b^{(2)}$ is bfloat16 and contains the least significant bits


## Let's have a more detailed look at dot-products

$z=\mathbf{x}^{T} \mathbf{y} \quad \hat{z}=|\mathbf{x}|^{T}|\mathbf{y}| \varepsilon_{f}=2^{-24} \gamma_{f, k}=\frac{k \varepsilon_{f}}{1-k \varepsilon_{f}}$
The standard computation in FP32 is as follows:
$Z \leftarrow 0$
For $\ell=1,2, \ldots, n$ :

$$
Z \leftarrow \operatorname{FMA}\left(x_{\ell}, y_{\ell}, Z\right)
$$

End
The error bound is standard in this case, namely

$$
|Z-z| \leqslant \gamma_{f, n} \hat{z}
$$

$\rightarrow$ "n rounding errors"

$$
\begin{aligned}
& Z^{(i, j)} \leftarrow 0 \\
& \text { For } \ell=1,2, \ldots, n: \quad \varepsilon_{b}=2^{-8} \\
& \quad Z^{(i, j)} \leftarrow \operatorname{FMA}\left(x_{\ell}^{(i)}, y_{\ell}^{(j)}, Z^{(i, j)}\right) \\
& \text { End } \\
& Z^{(0)} \leftarrow Z^{(0,0)} \\
& Z^{(1)} \leftarrow Z^{(0,1)}+Z^{(1,0)} \\
& Z^{(2)} \leftarrow Z^{(0,2)}+\left(Z^{(1,1)}+Z^{(2,0)}\right) \\
& Z^{(3)} \leftarrow Z^{(1,2)}+Z^{(2,1)} \\
& \begin{aligned}
Z^{(4)} \leftarrow & Z^{(2,2)} \\
\left|Z_{2}-z\right| & \leqslant\left|Z_{2}-\left(z^{(0)}+z^{(1)}+z^{(2)}\right)\right|+\left|z^{(3)}+z^{(4)}\right| \\
& \leqslant\left|Z_{2}-\left(z^{(0)}+z^{(1)}+z^{(2)}\right)\right|+1.01 \varepsilon_{b}^{3} \hat{z} \\
& \leqslant\left|Z_{2}-\left(Z^{(0)}+Z^{(1)}+Z^{(2)}\right)\right| \\
& \quad+\sum_{i=0}^{2}\left|Z^{(i)}-z^{(i)}\right|+1.01 \varepsilon_{b}^{3} \hat{z}
\end{aligned}
\end{aligned}
$$

$\rightarrow$ A split into 3 BF16 is slightly worse, but should not be relevant in practice

## Doing only the most relevant computations

| Number of Bfloat16s used in the split | Number of Multiplies to Do |
| :--- | :--- |
| 1 a1*b1 | 1 (bin 1 only) |
| 2 (a1,a2)*(b1,b2) | 3 (bins 1 and 2 only) |
| 3 (a1,a2,a3)*(b1,b2,b3) | 6 (bins 1, 2, and 3 only) |
| 4 (a1,a2,a3,a4)*(b1,b2,b3,b4) | 10 (bins 1-4 only) |

Add up the terms in this order: from the highest bin (likely smallest numbers) to the lowest bin (likely biggest numbers)

## But why do all this extra work??

- Because BFloat16 might be many times faster than FP32 in AVX-512.
- Suppose for the sake of argument, that it's 16x over FMA-based FP32 in AVX-512.
- 3 bfloats using 6 multiplies will have $\sim 6 x$ the flops
- There's still potential speed-up over FP32

| BF16 Speed- <br> Up <br> Over FP32 | Combined <br> BF16 <br> For FP32 |
| :---: | :---: |
| 8 | $1.3=8 / 6$ |
| 16 | $2.7=16 / 6$ |
| 32 | $5.2=32 / 6$ |

- Similar accuracy but faster (assuming the splits can be done relatively free)


## BF16x3 Can be Invisible to SGEMM (FP32 matrixmatrix multiply) users

- Different numeric results, but in many cases greater accuracy
- Time in BF16x3-GEMM is: the decomposition, matrix multiplication, adding up the results at the end.
- The middle matrix-multiply step is $\mathrm{O}\left(\mathrm{n}^{\wedge} 3\right)$ and must be done 6 times
- The first and last step are $O\left(n^{\wedge} 2\right)$ and must be done once
- Hopefully most of the time will be in GEMM...
- The data can "start" in FP32 format, and "finish" in FP32 format
- The results may be faster... Again, BF16 might be 8x-32x faster than FP32
- $6 x$ more computations executed at $16 x$ faster? A win!


## Okay, so it works but what do the experiments say?

- Tested lots of dot products with varying ranges
- Tested lots of GEMM variants and cases
- Small Range (Uniformly Random Distribution in a close range like [-1,1]
- Huge Range (Uniformly Random Exponents)
- Medium Range (Gaussian Distribution on the exponents)
- Tested LU decomposition


## Matrix Multiply - GEMM



SGEMM ( $\mathrm{M}=\mathrm{N}=\mathrm{K}$, Transa/b=N, Alpha=1, Beta=0) Problem Size $(8 \times 8,16 \times 16,32 \times 32$ or $64 \times 64)$
Various GEMM average relative error vs. DGEMM (||A x $B$ - DGEMM||/||DGEMM|| ) over 1000 runs compared to original fp64 data in [-1.0,1.0] range with drand48() randomization. bxA $\mathrm{B}[\mathrm{d}]$ means breaking each matrix up into A bfloat16 matrices, doing B products. Optionally, collect the final answer with "d" (double precision) or not.

## GEMM contd.

$4.20 \mathrm{E}-08$
$4.10 \mathrm{E}-08$
$4.00 \mathrm{E}-08$
$3.90 \mathrm{E}-08$
$3.80 \mathrm{E}-08$
$3.70 \mathrm{E}-08$
huge Range: Max. exponent distribution
medium Range: Gaussian
exponent distribution

## LU Factorization



SGETRF vs BFLOAT16x3 6 LU Decomposition: Element errors average improvement over a 100 runs for $N \times N$ square matrices with an extremely large range $\left[-1^{\wedge} 10,1^{\wedge 10}\right]$ and matrices with a small range $[-1,1]$

## Conclusions

DL focused hardware solutions (which implement such mixed-precision FMA units) can be utilized for higher precision linear algebra

- We can match the accuracy of SGEMM and friends using BF16 mixed precision FMAs only
- BF16 mixed precision FMAs are potentially much energy and space friendly than pure FP32 units

The solutions present can be transferred to FP16 FMA with FP32 accumulate and also be combined with iterative refinement operations (see our paper)

Thank you for your time

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## Worse case for the 3-bfloat split break-down?

- In general, accuracy is equivalent to FP32, but the worst case error is unfortunately worse.
- The "favorite bad" case is when due to being at the extreme negative exponent, none of the other bfloat16 numbers are non-zero.
- Suppose $x$ has an exponent of -126 and we wish: $x=b 1+b 2+b 3$
- b1 = bfloat(x), but suppose $x$ has lots of interesting bits in position 0-15, these will be lost on b1.
- $\mathrm{b} 2=\mathrm{b} 3=0$ (Special bad case because it's a conversion error.)
- So any errors involving (b1,b2,b3) will have identical accuracy as simply 1 bfloat16 conversion- in other words, typically 2-3 decimal places only

